

/coding

Code and Space

ARC 593 | DMS 606

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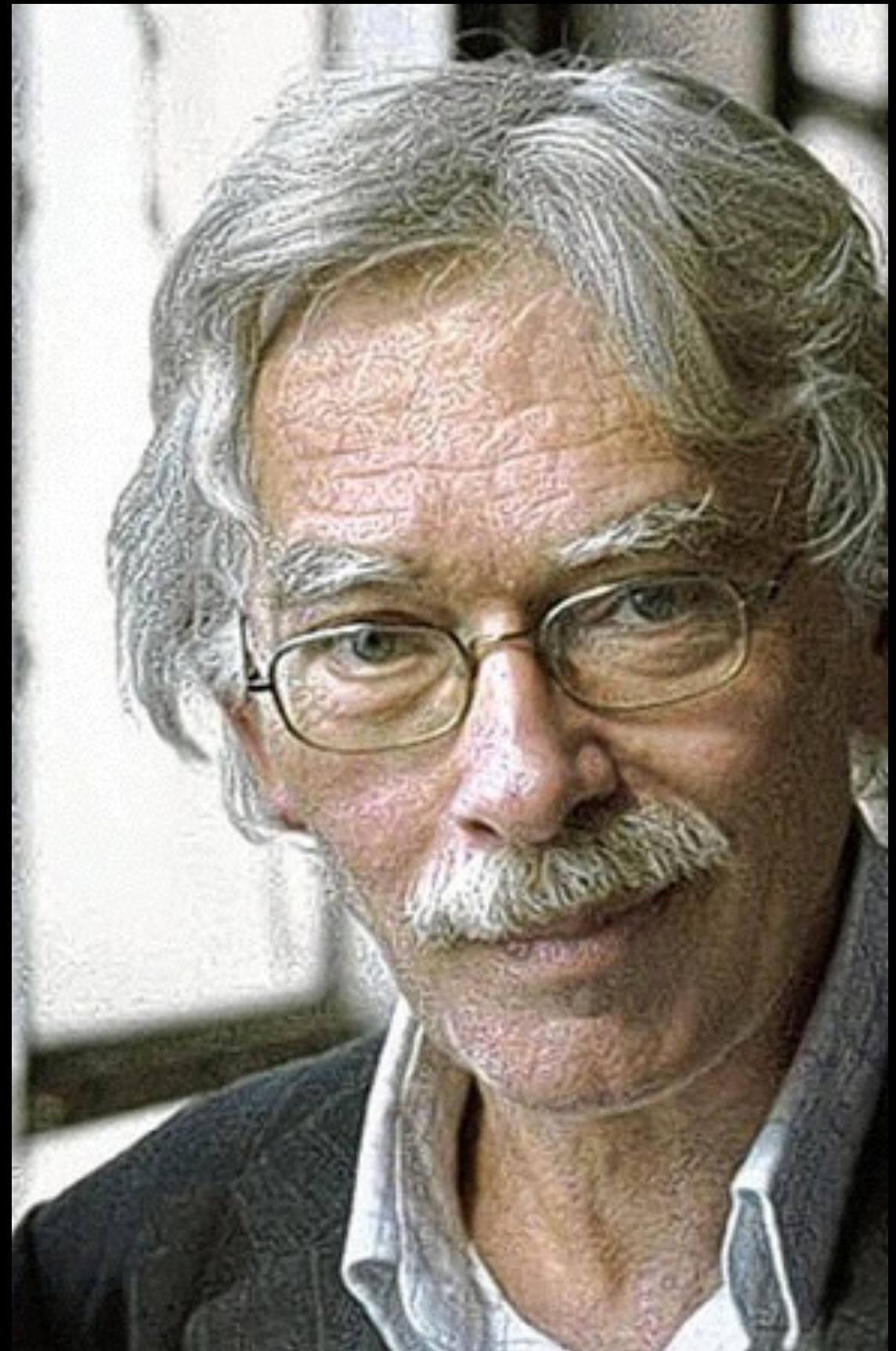
what is code?

The modern city exists as a haze of software instructions. (Amin and Thrift)

Values, opinions and rhetoric are frozen into code. (Bowker and Leigh-Star)

Frederich Kittler

Code, or How to Write
Something Differently



codes...

are the language of our time

- codes materialize the process of encryption
- Wolfgang Coy: “a mapping of a finite set of symbols of an alphabet onto a suitable signal sequence”

codes...

are not what what we may think:

- codes are not specific to computer technology or genetic engineering
- as sequences of signals over time, they are part of every communications technology

codes...

became conceivable/feasible given:

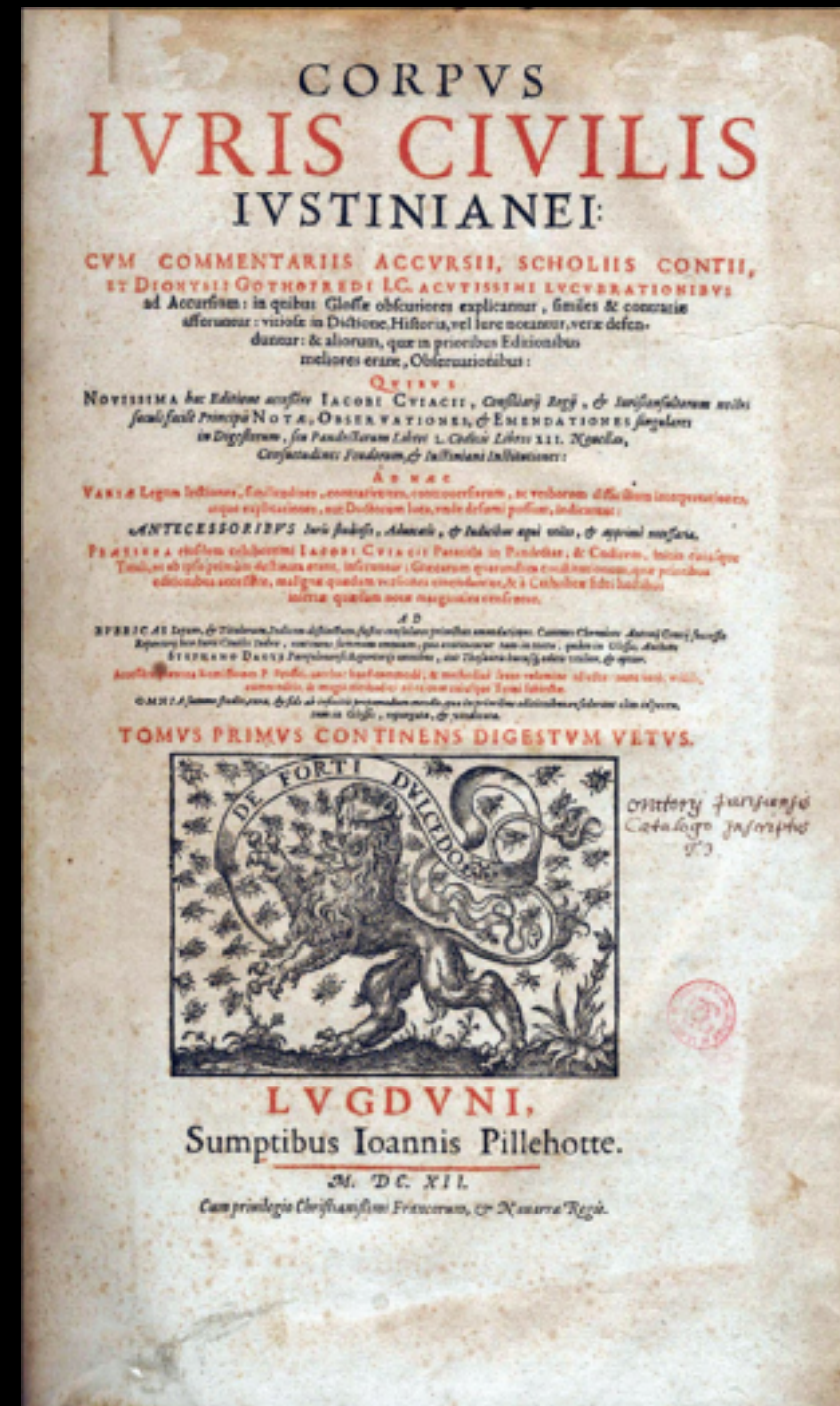
- alphabets that mapped speech sounds onto letters (more or less one-to-one)
- developed communications technology (secret messages, encryption)

codes...

command, code and communications

- command, code and communications technologies are brought together by the Empire
- code as the bound book of law
- codification as the judicial-bureaucratic act collecting imperial commands into a single collection of laws
- message transmission > data storage

the codex



codes...

morse code

- a system of writing optimized according to technical criteria (no regard to semantics)
- from deciphering / enciphering to encoding / decoding
- code is elegant if its output is longer than itself

codes...

morse code

A a	• —	J j	• — — —	S s	• • •
B b	— • • •	K k	— • —	T t	—
C c	— • — •	L l	• — • •	U u	• • —
D d	— • •	M m	— —	V v	• • • —
E e	•	N n	— •	W w	• — —
F f	• • — •	O o	— — —	X x	— • • —
G g	— — •	P p	• — — •	Y y	— • — —
H h	• • • •	Q q	— — • —	Z z	— — • •
I i	• •	R r	• — •		

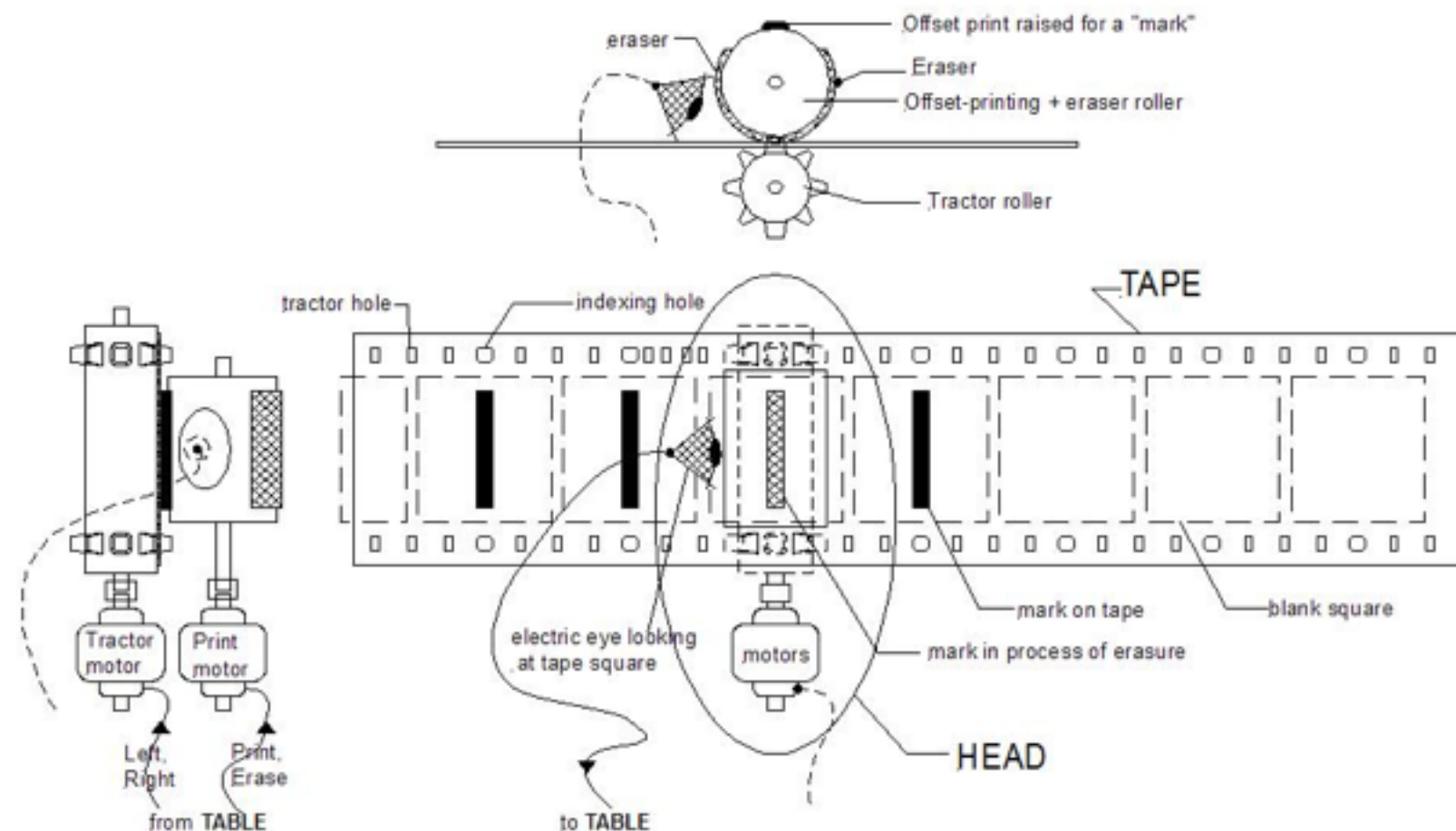
codes...

The Turing Machine (1936)

- convergence of mathematics and encryption
- an abstract machine that manipulates symbols on a strip of tape according to a table of rules
- a mathematical model of computation that defines such a device

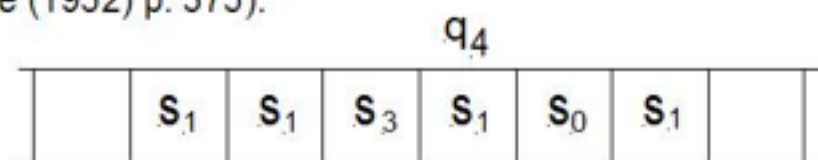
codes...

The Turing Machine (1936)



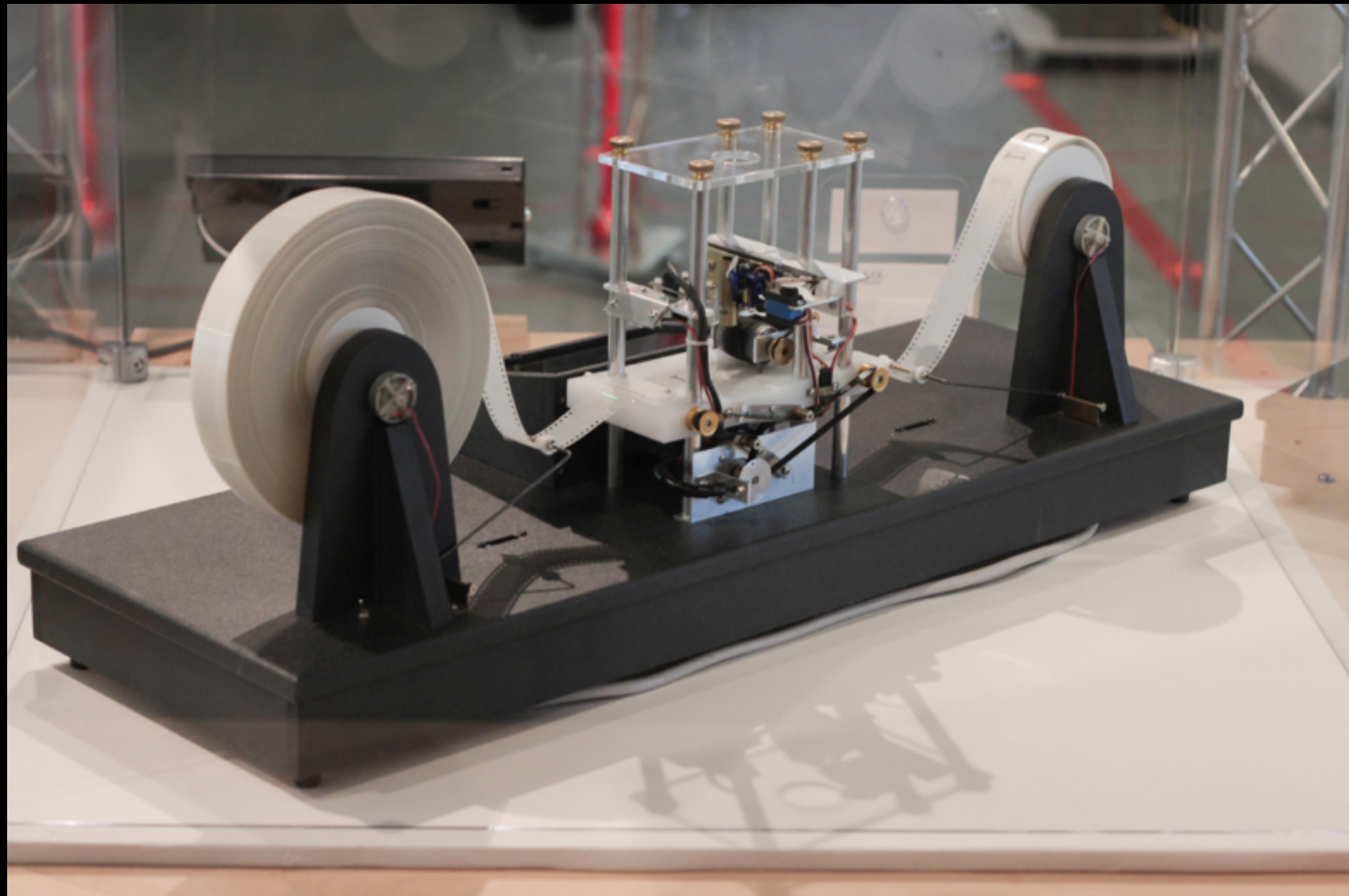
Above: a fanciful mechanical Turing machine's TAPE and HEAD (TABLE not shown).

Below: Usually Turing machines are drawn in a much simpler way -- as just a row of squares with symbols in them, the "head" drawn over the "square being scanned" (drawing after Kleene (1952) p. 375).



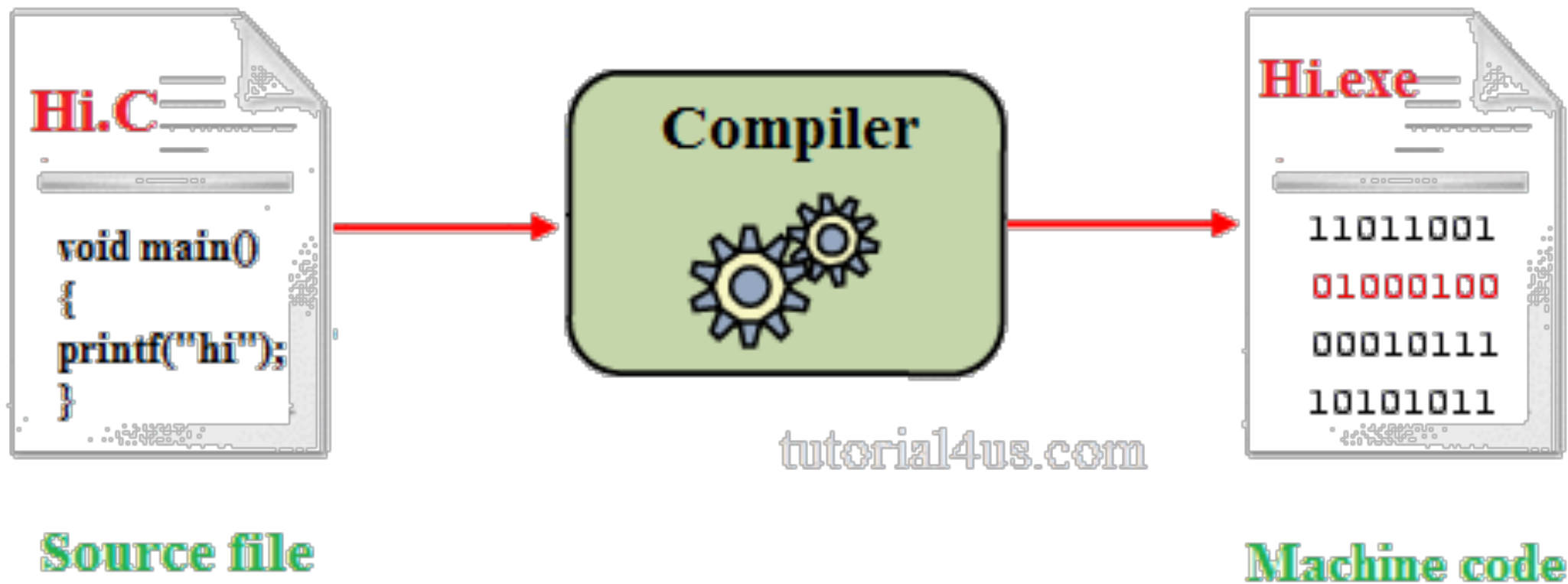
codes...

The Turing Machine (1936)



codes...

from high to low level language




```
/*
 * Blink
 *
 * The basic Arduino example. Turns on an LED on for one second,
 * then off for one second, and so on... We use pin 13 because,
 * depending on your Arduino board, it has either a built-in LED
 * or a built-in resistor so that you need only an LED.
 *
 * http://www.arduino.cc/en/Tutorial/Blink
 */

int ledPin = 13;                // LED connected to digital pin 13

void setup()                    // run once, when the sketch starts
{
    pinMode(ledPin, OUTPUT);    // sets the digital pin as output
}

void loop()                     // run over and over again
{
    digitalWrite(ledPin, HIGH); // sets the LED on
    delay(1000);                 // waits for a second
    digitalWrite(ledPin, LOW);  // sets the LED off
    delay(1000);                 // waits for a second
}
```

Comments

```
/*
 * Blink
 *
 * The basic Arduino example. Turns on an LED on for one second,
 * then off for one second, and so on... We use pin 13 because,
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    delay(1000);                // waits for a second
}
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/*
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 * then off for one second, and so on... We use pin 13 because,
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 * or a built-in resistor so that you need only an LED.
 *
 * http://www.arduino.cc/en/Tutorial/Blink
 */
```

Declare global variables

```
int ledPin = 13;           // LED connected to digital pin 13
```

```
void setup()               // run once, when the sketch starts
{
  pinMode(ledPin, OUTPUT); // sets the digital pin as output
}
```

```
void loop()                // run over and over again
{
  digitalWrite(ledPin, HIGH); // sets the LED on
  delay(1000);                // waits for a second
  digitalWrite(ledPin, LOW);  // sets the LED off
  delay(1000);                // waits for a second
}
```



```
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 * Blink
 *
 * The basic Arduino example. Turns on an LED on for one second,
 * then off for one second, and so on... We use pin 13 because,
 * depending on your Arduino board, it has either a built-in LED
 * or a built-in resistor so that you need only an LED.
 *
 * http://www.arduino.cc/en/Tutorial/Blink
 */
```

```
int ledPin = 13;           // LED connected to digital pin 13
```

Initial function call

```
void setup()               // run once, when the sketch starts
{
  pinMode(ledPin, OUTPUT); // sets the digital pin as output
}
```

```
void loop()                // run over and over again
{
  digitalWrite(ledPin, HIGH); // sets the LED on
  delay(1000);                // waits for a second
  digitalWrite(ledPin, LOW);  // sets the LED off
  delay(1000);                // waits for a second
}
```

```
/*
 * Blink
 *
 * The basic Arduino example. Turns on an LED on for one second,
 * then off for one second, and so on... We use pin 13 because,
 * depending on your Arduino board, it has either a built-in LED
 * or a built-in resistor so that you need only an LED.
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 * http://www.arduino.cc/en/Tutorial/Blink
 */

int ledPin = 13;                // LED connected to digital pin 13

void setup()                    // run once, when the sketch starts
{
    pinMode(ledPin, OUTPUT);    // sets the digital pin as output
}
```

Main program function, called infinitely

```
void loop()                     // run over and over again
{
    digitalWrite(ledPin, HIGH); // sets the LED on
    delay(1000);                 // waits for a second
    digitalWrite(ledPin, LOW);  // sets the LED off
    delay(1000);                 // waits for a second
}
```

Comments

Comments are notes to you (or others trying to understand your code) that are ignored by the program interpreter.

```
/*  
 * Blink  
 *  
 * The basic Arduino example. Turns on an LED on for one second,  
 * then off for one second, and so on... We use pin 13 because,  
 * depending on your Arduino board, it has either a built-in LED  
 * or a built-in resistor so that you need only an LED.  
 *  
 * http://www.arduino.cc/en/Tutorial/Blink  
 */
```

```
// this is a single line comment
```

```
/* this is how you start a multiline comment  
and this is how you end it */
```

Anything between the first `/*` and the next `*/` will be ignored

Variables

Variables are places to store data you use more than once.

```
int ledPin = 13;           // LED connected to digital pin 13
```

box type	box name	=	box contents
int	ledPin	=	13

The first part of the line before the comment is called a **statement**. All statements end with a semicolon ;

Think of variables as boxes where you store different kinds of data. In this case, **int** means “integer” or simply a whole number.

This **statement** creates a box called **ledPin** and stores the integer **13** in this box.

Variables

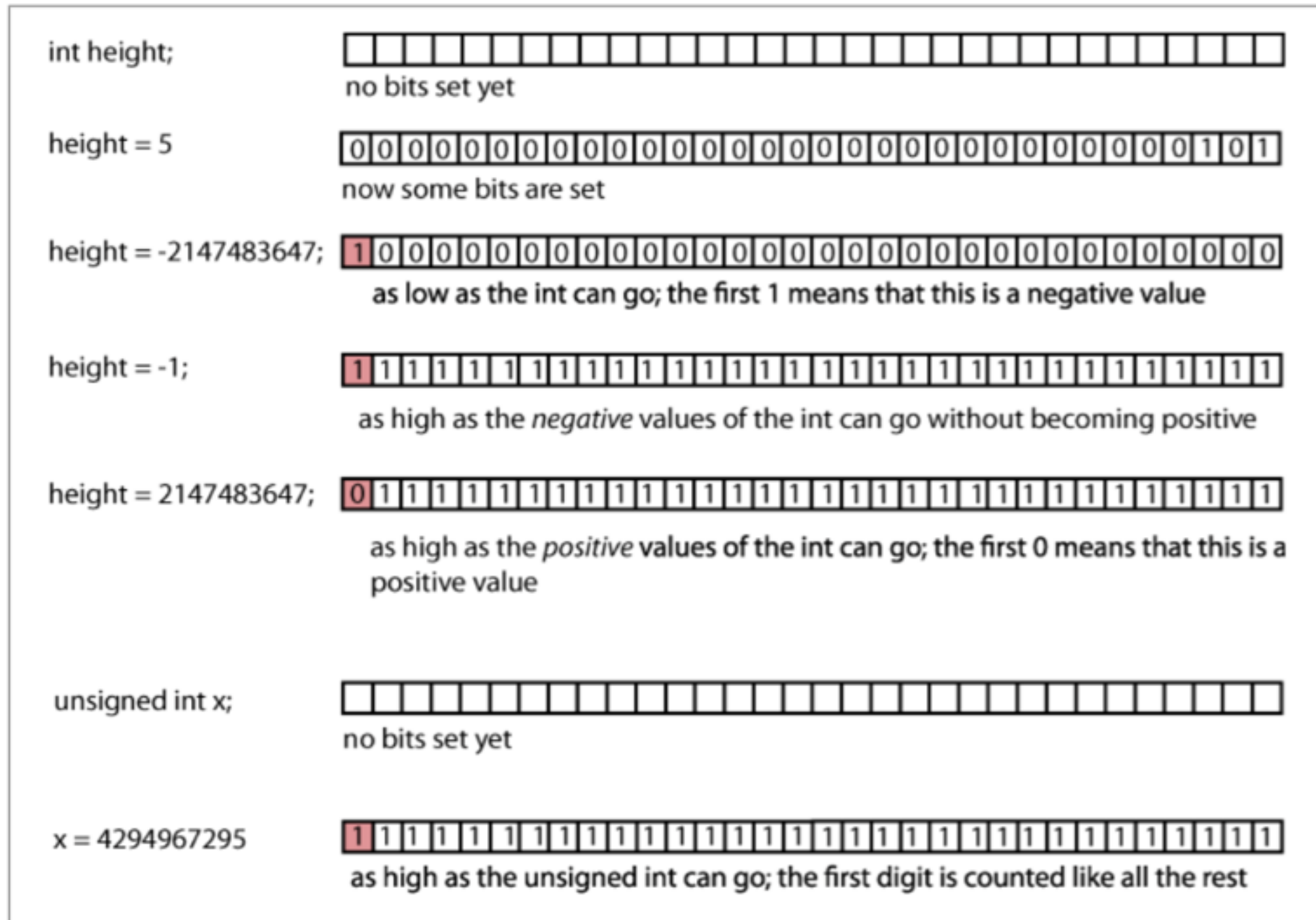


Figure 2-1. Setting the bits of signed and unsigned variables

Data types

Different kinds of data need different kinds of boxes.
Here are some different kinds of boxes you can use:

- void
- boolean
- char
- unsigned char
- byte
- int
- unsigned int
- word
- long
- unsigned long
- float
- double
- string - char array
- String - object
- array

(Click on each data type for more detail.)

Array

An array is a collection of variables that are accessed with an index number.

```
int myInts[6];  
int myPins[] = {2, 4, 8, 3, 6};  
int mySensVals[6] = {2, 4, -8, 3, 2};  
char message[6] = "hello";
```

You can **declare** an array without initializing it as in myInts.

In myPins we declare an array without explicitly choosing a size. The compiler counts the elements and creates an array of the appropriate size.

Finally you can both initialize and size your array, as in mySensVals. Note that when declaring an array of type char, one more element than your initialization is required, to hold the required null character.

Array

Arrays are zero indexed, that is, referring to the array initialization above, the first element of the array is at index 0, hence:

```
int mySensVals[6] = {2, 4, -8, 3, 2};  
mySensVals[0] == 2, mySensVals[1] == 4, [...]
```

It also means that in an array with ten elements, index nine is the last element. So:

```
int myArray[10]={9,3,2,4,3,2,7,8,9,11};  
// myArray[9]      contains 11  
// myArray[10]     is invalid and contains random information  
                  (other memory address)
```

To assign a value to an array:

```
mySensVals[0] = 10;
```

To retrieve a value from an array:

```
x = mySensVals[4];
```

Control Structures

Control structures enable you to execute different blocks of code depending on different conditions - such as if a switch is on or off, or if a sensor exceeds a certain threshold, for example.

Here are some control structures you can use in Arduino:

- if
- if...else
- for
- switch case
- while
- do... while
- break
- continue
- return
- goto

(Click on each data type for more detail.)

if statement

If a (condition) is true, then execute the following statement(s). If not, do nothing.

```
if (buttonState == HIGH) {  
    digitalWrite(ledPin, HIGH);    // turn LED on:  
}
```

control	(condition)	{statements}
if	(buttonState == HIGH)	{ digitalWrite(ledPin, HIGH); }

Here are comparison operators you can use in your conditional statements (click for more info):

- `==` (equal to)
- `!=` (not equal to)
- `<` (less than)
- `>` (greater than)
- `<=` (less than or equal to)
- `>=` (greater than or equal to)

if ... else

```
int buttonPin = 2;    // the number of the pushbutton pin
int ledPin = 13;      // the number of the LED pin
int buttonState = 0;  // variable for reading the pushbutton status

void setup() {
  pinMode(ledPin, OUTPUT); // initialize the LED pin as an output
  pinMode(buttonPin, INPUT); // initialize the pushbutton pin as an input
}

void loop(){
  buttonState = digitalRead(buttonPin); // read the state of the pushbutton
  // check if the pushbutton is pressed - if it is, the buttonState is HIGH:
  if (buttonState == HIGH) {
    digitalWrite(ledPin, HIGH); // turn LED on:
  }
  else {
    digitalWrite(ledPin, LOW); // turn LED off:
  }
}
```

// adapted from <http://www.arduino.cc/en/Tutorial/Button>

for

The **for** statement is used to repeat a block of statements enclosed in curly braces.

An increment counter is usually used to increment and terminate the loop.

```
for (initialization; condition; increment) {  
    //statement(s);  
}
```

for

The **initialization** happens first and exactly once. Each time through the loop, the **condition** is tested; if it's true, the **statement** block, and the **increment** is executed, then the **condition** is tested again. When the **condition** becomes false, the loop ends.

The diagram illustrates the components of a for loop using the example code: `for(int x = 0; x < 100; x++) { println(x); // prints 0 to 99 }`. Annotations with arrows point to specific parts of the code: a blue arrow labeled 'parenthesis' points to the opening curly brace; a teal arrow labeled 'declare variable (optional)' points to `int x`; a purple arrow labeled 'initialize' points to `= 0`; a purple arrow labeled 'test' points to `x < 100`; and a purple arrow labeled 'increment or decrement' points to `x++`. A large orange curved arrow starts from the top of the loop body and points back to the test condition, representing the loop's iteration cycle.

```
for(int x = 0; x < 100; x++) {  
    println(x); // prints 0 to 99  
}
```

for

Dimming an LED using a PWM pin and a for loop

```
// Dim an LED using a PWM pin

int PWMpin = 10; // LED in series with 470 ohm resistor on pin 10

void setup()
{
    // no setup needed
}

void loop()
{
    for (int i=0; i <= 255; i++){
        analogWrite(PWMpin, i);
        delay(10);
    }
}
```

Functions

void setup() is a **function** that is called once, when the program starts.

```
void setup()           // run once, when the sketch starts
{
  pinMode(ledPin, OUTPUT); // sets the digital pin as output
}
```

returned value	function name	(input values)	{statements}
void	setup	()	{ pinMode(ledPin, OUTPUT); }

Functions are collections of **statements**. We use **functions** to group together a set of **statements** we want to be able to refer to with one name.

Functions

```
clean_dishes wash_the_dishes(dirty_dishes)
{
  place dirty_dishes in the sink;
  turn on hot water;
  if the water is too hot, turn on cold water too;
  put on some LCD SOUNDSYSTEM to abate boredom;
  add soap to water;
  while dirty_dishes are dirty,
    scrub dirty_dishes until they are clean;
  return clean_dishes to cabinet;
}
```

returned value	procedure name	(input values)	{statements}
clean_dishes	wash_the_dishes	(dirty_dishes)	{ ... }

Function calls

void loop() is a **function** that is called repeatedly, until the program ends. This is the main function of your program.

```
void loop()                // run over and over again
{
  digitalWrite(ledPin, HIGH); // sets the LED on
  delay(1000);               // waits for a second
  digitalWrite(ledPin, LOW);  // sets the LED off
  delay(1000);               // waits for a second
}
```

procedure name	(input value)	;
delay	(1000)	;

This **statement** calls the built-in **delay() function**, passing the **input value** of 1000.

```
void delay(number of milliseconds)
{
  stop and wait for (number of milliseconds);
}
```

Custom functions

You can write your own functions to group a series of statements that you want to execute repeatedly from different places in your code.

First, define your function:

```
void blink()  
{  
    digitalWrite(ledPin, HIGH);  
    delay(1000);  
    digitalWrite(ledPin, LOW);  
    delay(1000);  
}
```

Then call that function from within your program somewhere:

```
void loop()  
{  
    blink();  
}
```